



**INVERTER** 

FR-E800

Digest Edition





# Design future manufacturing

# FR-E800—World's smallest class inverter with high functionality

Ever since the Industrial Revolution,

manufacturing technologies have evolved over the years.

And now, this is the time for new revolution.

A new era has started. Inverters are connected to the world.

We design future manufacturing and what's ahead.





E800-E Ethernet model

E800-SCE Safety communication model











Real-time connection with the host IT system enables centralized or remote monitoring of operation, which further streamlines the production.

Improving usability by supporting CC-Link IE TSN as standard

Real-time production data can be collected using efficient protocols, and multiple protocols are supported on the same network, which provides a smart connection solution with various devices.

>> P11 CC-Línk**IE TSN** 

Expanding a range of applications with multi-protocols

Multi-protocol support enables switching between various types of communication

Inverter models that support major global industrial Ethernet networks are available.

EtherNet/IP **PROFINET EtherCAT** 

>> P11

**Enabling flexible connection with two Ethernet ports** 

There is no need to use a switching hub.

**Two Ethernet** ports

>> P12

Al technology and smartphone connectivity support initial startup or troubleshooting. Extensive maintenance functions will contribute to improvement in maintainability.

Reducing downtime using the AI function

The Al fault diagnosis function is used to identify the cause of a fault, enabling the fastest troubleshooting procedure.

Al fault diagnosis

>> P25

**Enhancing predictive maintenance** 

Integrating the world's first\*1 corrosive gas environment detection circuit\*2 makes it possible to identify signs of inverter damage caused by corrosive gas. The corrosion diagnosis function for the control circuit board enables visualization of the environment where the inverter is installed, enhancing maintainability and preventing faults.

**Control circuit** board corrosion diagnosis

>> P22

\*1: According to our investigation as of September 10, 2019.

\*2: Patent pending

Further facilitating operation with your smartphone

Using smartphones or tablets, you can scan the QR code on the product to access the setup information, or you can access inverters via wireless remote network with a mobile app. This will contribute to reduction in startup time and improvement in maintainability.

**Engineering** software

>> P26

# Safety

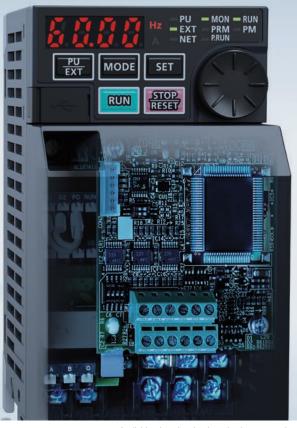
Advanced harmony between humans and FA devices



# Performance



Various solutions
achieved by the outstanding
drive performance





#### Various safety monitoring functions and wireless inverter connection enable stable and safe operation of the system.

#### Attaining both safety and productivity

Speed monitoring functions ensure safe operation for users.

SLS function\*1 (Safely-limited speed)

>> P19

#### Reducing the costs for safety

The inverter is compliant with safety integrity level (SIL) 3 of the IEC 61508 standard for functional safety. This will contribute to reduction in the initial safety certification cost. Furthermore, safety products can be used on the existing network as safety communication protocols are supported.

**Functional safety** >> P19

#### **Ensuring operators' safety by wireless interfaces**

Adjustments of inverter parameters and inverter monitoring can be performed wirelessly away from the system, ensuring operators' safety.

**Ethernet** connection\*1

>> P18

\*1: Several conditions must be met to use this function.

#### Various control methods are supported to expand applications in many systems.

#### Supporting various control methods

Various control methods such as Vector control (with encoder), Real sensorless vector control (without encoder), and positioning without using sensors are supported. Premium efficiency motors and PM motors are supported, enabling applications in various solutions.

Control method >> P17

#### Expanding applications with the enhanced product line

The product line is enhanced as compared to the preceding FR-E700 inverters.

- 18.5 kW / 22 kW supported
- 575 V class supported
- Surrounding air temperature of -20°C to 60°C\*1
- Compliance with IEC 60721-3-3(3C2)\*2 for corrosive gas concentration
- IP67 models (FR-E846)

**Extended capacity** range / improved environmental resistance

>> P14

<sup>\*1:</sup> Derating required for 50°C or higher.

<sup>\*2:</sup> Coated model (-60) only

# Useful functions for each of the design, operation, and maintenance processes of systems

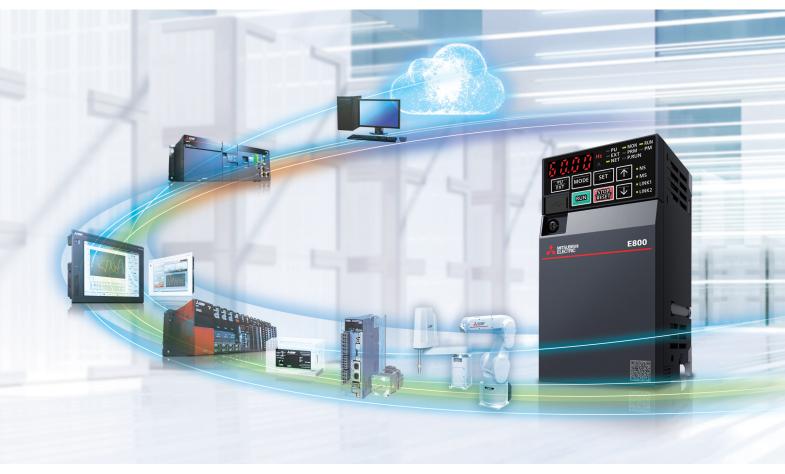
FR-E800 inverters have various functions to attract more customers by offering safe and reliable operation for a long time.

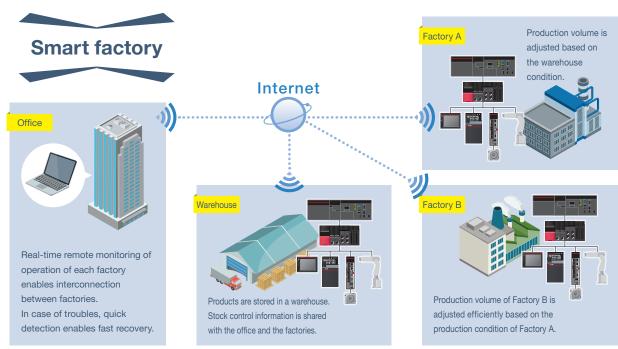
This is the time to start innovation in the fields of manufacturing.

	1		Smart factory Supporting various networks enable flexible system design.	P10-13
Design	2	K A K Y	Wide range of applications The extended range of capacities and dimensions supports various applications.	P14·15
	3	3	Higher added values  The outstanding drive performance and various functions create higher added values.	P16·17
Operation	4	•	Improved safety Humans and FA devices can work together by enhancing functional safety.	P18·19
Operation	5	4	Energy saving Use of induction motors or IPM motors contributes to energy saving.	P20·21
Maintenance	6	Yi	Improved maintainability Functions for residual life diagnosis, predictive maintenance, and preventive maintenance support stable system operation.	P22·23
Maintenance	7	Q	Downtime reduction When a fault occurs, AI analysis and other diagnosis functions solve the problem quickly.	P24·25
		No.		
Engineering tools	8		Engineering software for further ease of operation  The work efficiency can be improved for each of the design, operation, and maintenance processes.	P26-29



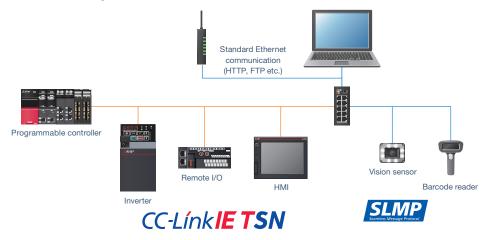
Supporting various networks enable flexible system design.





#### Less workload required for system construction E800 E800-E E800-SCE CC-Link IE TSN supported as standard • Deterministic performance of cyclic communication is CC-Línk**IE TSN** maintained even when mixed with slower information data (non real-time). This enables TCP/IP communication devices to be used without affecting overall control. Network device profiles are available to facilitate network construction. Data communication Control communication Data communication band Link scan time occupancy rate (%) Control communication band Network load diagram

• Non-FA devices that support SLMP and TCP/IP communication can also connect to the network. Inverters can connect to a variety of devices, enabling use with versatile devices.



#### 2 Compatibility with global networks

E800 E800-E E800-SCE

#### Multi-protocols

Inverter models with the integrated function to support major global industrial Ethernet networks are available. FR-E800 inverters support a variety of open networks without using any options, enabling the use of inverters on the existing

network and assuring compatibility with various systems. Users can select a protocol group suitable for the intended system. It is possible to switch between protocols only by setting parameters. (Supported protocols differ depending on the model.)

#### Supported protocols

				-			
Model	CC-Link IE TSN (100Mbps)*1	CC-Link IE Field Network Basic	MODBUS®/TCP	PROFINET	EtherNet/IP	BACnet/IP	EtherCAT
FR-E800-[]EPA	•	•	•	_	•	•	_
FR-E800-[]EPB	0	•	•	•	_	_	_
FR-E800-[]EPC	_	_	_	_	_	_	0

<sup>\*1: 1</sup> Gbps is optional (to be supported)

●: Supported ○: To be supported soon



Supporting various networks enable flexible system design.

#### 3 Supporting various topologies

E800 E800-E E800-SCE

#### ► Two Ethernet ports

Two Ethernet ports are provided as standard, enabling flexible connection in line topology without using a switching hub. (A compatible master module is required for ring topology.)

Complex networks can be created just by connecting devices with a cable to a free port.

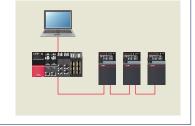
The network can even accommodate changes in the specifications of devices.



#### Line topology

The total wiring length can be minimized for large or extensive systems.

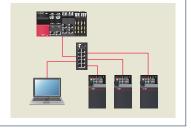
Eliminating a switching hub allows more flexible installation of inverters even in a



#### Star topology

narrow space.

A fault in one device does not affect other devices. Fast recovery is enabled when a fault occurs as it is easy to know which device is faulty.

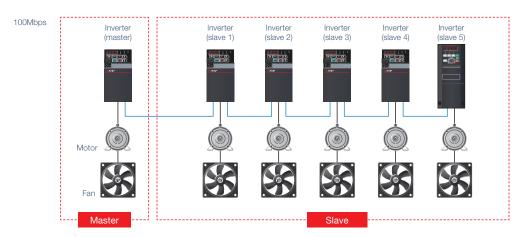


4 Enabling construction of a small-scale synchronous system of inverters

E800 E800-E E800-SCE

#### ► Inverter-to-inverter link function

Communication between multiple inverters is carried out through the I/O device and special register transmission of the PLC function (refer to page 16). A small-scale system can be created by connecting multiple inverters via Ethernet. (The FR-A800-E inverter or the FR-F800-E inverter can be mixed in the system.)



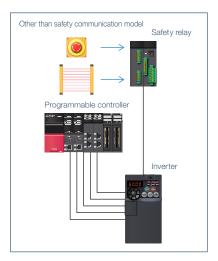
#### **5** Simple configuration with less wiring using safety communication models

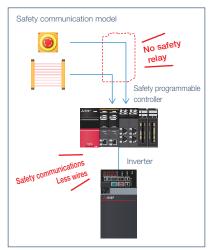
E800-SCE E800 E800-E

Safety communication model To be supported soon

Safety communication models support Ethernet-based safety communication protocols certified as compliant with international standards. Safety products can be used on the existing network as safety communication protocols are supported. Safety control can be introduced while reducing the initial cost.

- CC-Link IE TSN Safety Function
- PROFISafe
- CIP Safety
- FSoE (Safety over EtherCAT)





#### **6** Security measures

#### Ethernet IP filtering function

Set the IP address range for connectable network devices to limit connectable devices.

The Ethernet IP filtering function is a means to prevent unwanted access from external devices, but it does not prevent it completely.

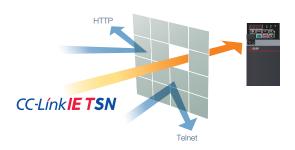


#### ► Ethernet command source selection

Devices which can control the inverter can be limited by setting the IP address range of the network device(s) used to operate it.

#### Ethernet function selection

Communication sockets are created only for selected applications such as CC-Link IE TSN or MODBUS/TCP to prevent unwanted access.



The extended range of capacities and dimensions supports various applications.



#### Supporting various systems and environments

#### Extended capacity range

The product line will be extended to include 18.5K and 22K inverters. This will allow use of inverters in large-scale systems.

#### Increased environmental resistance

Various applications are supported by allowing for corrosive environments or a wide range of surrounding air temperatures.

- Surrounding air temperatures between -20°C and 60°C\*¹ are supported. (-10°C to +50°C for the FR-E700)
- Inverters with circuit board coating (IEC 60721-3-3(3C2))\*2 are available for improved environmental resistance.
- \*1: Derating required for 50°C or higher.
- \*2: Coated model (-60) only.

E800

E800-E

E800-SCE



Water treatment plant



Painting line

#### 2 Effective solution for downsizing equipment

E800-E E800-SCE

#### Double ratings

Two rating types of different rated current and permissible load can be selected by setting parameters. The choice of inverters is widened for intended applications of users. When users select the LD rating for light duty applications, inverters with smaller capacities can be used as compared to the FR-E700 series inverters. For example, when the LD rating (light duty) is selected for a 22K inverter, the inverter can drive a motor with a capacity up to 30 kW.

Load		Overload current rating
Light duty	LD rating	120% 60 s, 150% 3 s (inverse-time characteristics) at surrounding air temperature of 50°C
Normal duty	ND rating	150% 60 s, 200% 3 s (inverse-time characteristics) at surrounding air temperature of 50°C



Building water pumps

#### 3 Optimizing the layout inside the enclosure

#### ► Flexible installation

When the surrounding air temperature is 40°C or less, multiple inverters can be installed side-by-side. Users can select the most suitable layout for the intended installation area.



Side-by-side installation

#### E800 E800-E E800-SCE



Ceiling crane

#### 4 Enabling installation in various environments

► IP67 models (400 V class: 0.75K to 3.7K) To be supported soon

Installation outside of the enclosure enables installation closer to machines (FR-E846). Since the inverter is compatible with hostile environments such as high humidity and dusty environments, users can easily install the inverter near the machine or in available spaces.

It is possible to reduce line noise by shortening the wiring length between the inverter and the motor.





Automotive production line

#### Improving productivity with shorter tact time by the enhanced regeneration function

E800-E

E800-SCE

#### Built-in brake transistor

With the enhanced power regeneration capability (brake duty: 100% max.), deceleration time can be shortened.\*1

\*1 : For 200 V class 0.4K and 0.75K models, the brake duty is 30% ED maximum when the lowest resistance value is used. The brake resistor must have a sufficient capacity to consume the regenerative power

For 200 V class 0.1K and 0.2K models, brake transistors are not built in.



When the increased magnetic excitation deceleration function is used, the motor consumes the regenerative power and the deceleration time can be reduced without using a brake resistor.

The tact time can be reduced for a transfer line or the like.



Automotive production line



Airport baggage conveyor

# Design Higher added values

The outstanding drive performance and various functions create higher added values.



#### ■ Customizing inverter operation for each machine

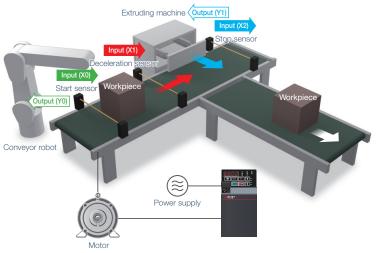
E800

E800-E

E800-SCE

#### **PLC** function

In accordance with the machine specifications, users can set various operation patterns: inverter movements at signal inputs, signal outputs at particular inverter statuses, and monitor outputs, etc. Operation of the system can be customized by the inverter alone.



#### 2 Same spare inverters for various applications

E800 E800-E E800-SCE

#### Control method

Switching between control methods with the FR-E800 inverter, Vector control for lift application (with the plug-in option), Advanced magnetic flux vector control for conveyors, etc., reduces the number of required spare inverters.

PM sensorless vector control is available when inverters are used with PM motors. High-level control such as positioning control is enabled without using an encoder (to be supported).

#### Offline auto tuning

Sensorless operation can be performed with non-Mitsubishi Electric general-purpose (induction) motors\*1 and permanent magnet (PM) motors\*1 as well as Mitsubishi Electric induction motors and PM motors.

Users can use existing motors with new inverters.

Control	Speed control	Torque control	Position control	Motor	
V/F control	•	-	-		
Advanced magnetic flux vector control	•	-	-	Induction	
Real sensorless vector control	•	•	-	motor	
Vector control (with plug-in		0	0	motor	
option FR-A8AP E kit used)	0		0		
PM sensorless vector control	•	-	0	PM motor	

•: Supported O: To be supported

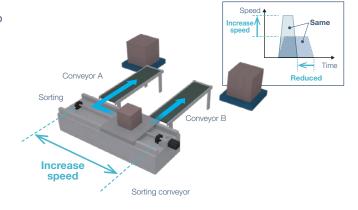


#### 3 Improving work efficiency by powerful high-speed operation

E800 E800-E E800-SC

#### ▶ PM sensorless vector control

The torque is not reduced in the high-speed range (up to the rated speed) during PM sensorless vector control as compared with operation using a stepper motor. High-speed system operation improves the tact time.



## 4 Expanding the range of applications using inverter options

#### Plug-in options

In addition to the existing plug-in options to add digital inputs / analog outputs and to support different communication standards, the Vector control compatible option FR-A8AP E kit is supported. Among our compact inverters, FR-E800 inverters are the first to support Vector control.

#### E800 E800-E E800-SCE

#### FR-E800 inverter options

Model	Description	Supported
FR-A8AX E kit	16-bit digital input	•
FR-A8AY E kit	Digital output, additional analog output	•
FR-A8AR E kit	Relay output	•
FR-A8AP E kit	Vector control, encoder feedback control	0
FR-E8DS E kit	24VDC input	0
FR-A8NC E kit	CC-Link	•
FR-A8ND E kit	DeviceNet	0
FR-A8NP E kit	PROFIBUS-DP	0

•: Supported O: To be supported

<sup>\*1:</sup> Tuning may be disabled depending on the motor characteristics.

# Improved safety

Humans and FA devices can work together by enhancing functional safety.

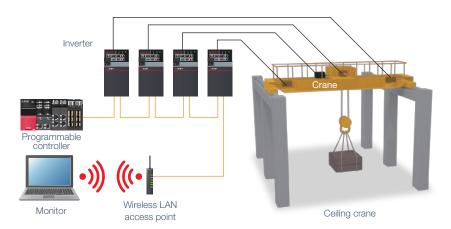


#### **■** Wireless access with hard-to-reach inverters

E800 E800-E E800-SCE

#### **▶** Ethernet communication

Even if inverters are located in a high place, narrow area, or other hard-to-reach place, wireless access enables adjustments of inverter parameters, inverter monitoring (simultaneous monitoring of multiple axes possible), and inverter maintenance such as life diagnosis checks. The FR-E800 inverter can be connected to FR Configurator2 using a commercially-available industrial wireless LAN\*1 access point.\*2



- \*1: A wireless LAN suitable for the industrial use in severe environments or in environments requiring high reliability (redundancy).
- \*2: Under certain environments or installation conditions, Ethernet communication through wireless LAN is not as stable as communication through wired LAN. Before starting operation, always check the communication status. Inverter operation (output shutoff, deceleration stop, etc.) when communication fails (due to reasons such as disconnection) can be selected by setting parameters. For applications requiring data transmission or update periodically or within a certain time period, a wired connection is recommended.

#### 2 Attaining both safety and productivity

E800-E E800-SCE

#### Functional safety

The inverter is compliant with safety integrity level (SIL) 3 of the IEC 61508 standard for functional safety. This will contribute to reduction in the initial safety certification cost. The following safety functions (IEC 61800-5-2) are supported without using external devices such as an encoder. Several conditions must be met to use this function.

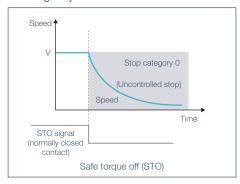
This will significantly reduce time required for maintenance or tooling and eliminate external devices such as ones used for monitoring the speed.

		FR-E800, FR-E800-E	FR-E800-SCE	FR-E700-SC
Functional safety category (ISO 13849-1, IEC 61508)		SIL2, PLd, Cat.3	SIL3, PLe, Cat.3	SIL2, PLd, Cat.3
STO	Safety torque off, coasting to stop	•	0	•
SS1	Safe stop 1, deceleration stop	-	0	-
SLS	Safely-limited speed	-	0	_
SBC	Safe brake control	-	0	-
SSM	Safe speed monitor	_	0	_

•: Supported O: To be supported -: Not supported

#### STO (safe torque off) function

The shutoff circuit (hardware) securely shuts off the output in case of emergency.



Driving power to the motor is electronically shut off by responding to the input signal from external equipment (output shutoff).

#### E800 E800-E E800-SCE Without STO function Functional safety integrated Safety stop function (STO) cuts down the number of MCs to one! Magnetic contactor (MC) • Emergency stop wiring With STO function

\*1: One MC is required to shut off the power at an act

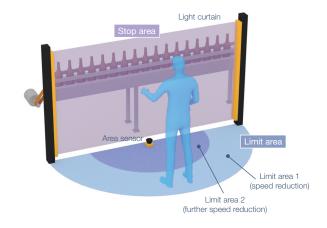
#### SLS (safely-limited speed) function To be supported soon

It is possible to continue operation at a safe speed without stopping the production line.

The motor speed is calculated based on the current value or other data without using an encoder. This will contribute to wire and cost savings.



Function to monitor the speed so that the predetermined speed limit is not exceeded.



E800

FR-E800

E800-E

E800-SCE



Use of induction motors or PM motors contributes to energy saving.



#### **■** Energy saving with motors

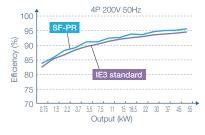
E800

E800-E

E800-SCE

#### General-purpose motor (SF-PR)

The Mitsubishi Electric SF-PR high-performance energy saving motor conforms to the Japanese domestic Top Runner Standard (IE3 equivalent). Its energy-saving operation contributes reduction in the electricity charges, which in turn lowers the running cost. Motor constants are stored in the inverter. Energy-saving operation can be started just by setting parameters.



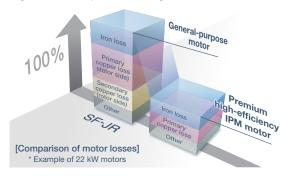
#### ► PM motor

The PM motor achieves even higher efficiency as compared to the general-purpose motor (SF-JR).

The setting for driving PM motors is enabled just by setting parameters.

Why is a PM motor so efficient?

- No current flows to the rotor (secondary side), and no secondary copper loss is generated.
- Magnetic flux is generated with permanent magnets, and less motor current is required.



#### 2 Supporting step-by-step energy saving solution

E800

E800-E

E800-SCE

#### Compatibility with both induction motors and PM motors

Further energy saving operation is enabled by using IE3/IE4 induction motors or permanent magnet embedded (PM) motors.

FR-E800 inverters support both induction motors and PM motors, enabling step-by-step replacement of existing devices. Users can replace inverters first and then motors. There is no need to replace them all at once.

#### **Equipment investment in stages** 1st Step Update First, replace inverters. complete / FR-E700 FR-F800 General-purpose 2nd Step Next, replace motors.

#### 3 Energy saving with inverters

#### Advanced optimum excitation control

To be supported soon

A large starting torque can be provided with the same motor efficiency under Optimum excitation control. Without the need of troublesome adjustment of parameters (acceleration/deceleration time, torque boost, etc.), acceleration is done in a short time. Also, energy saving operation with the utmost improved motor efficiency is performed during constant-speed operation.

When Advanced magnetic flux vector control is selected, Advanced optimum excitation control is available.

#### Energy saving monitoring

The energy saving effect can be checked using an operation panel, output terminal, or network.

The output power amount measured by the inverter can be output in pulses. The cumulative power amount can be easily checked.\*1

\*1: This function cannot be used as a meter to certify electricity billings.

#### 4 Energy saving with the regenerative option

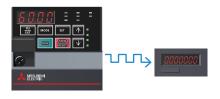
#### Power regeneration function (optional)

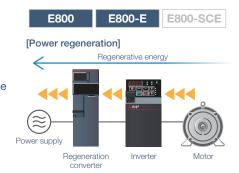
While the motor rotates to drive the machine during power driving, the machine rotates the motor during regenerative driving, which results in energy saving since the motor serves as a generator which returns the power to the power supply. By using the multifunction regeneration converter (FR-XC) as a common converter, the power returned from an inverter during regenerative drive can be supplied to another inverter, which in turn saves energy.

E800

E800-E E800-SCE

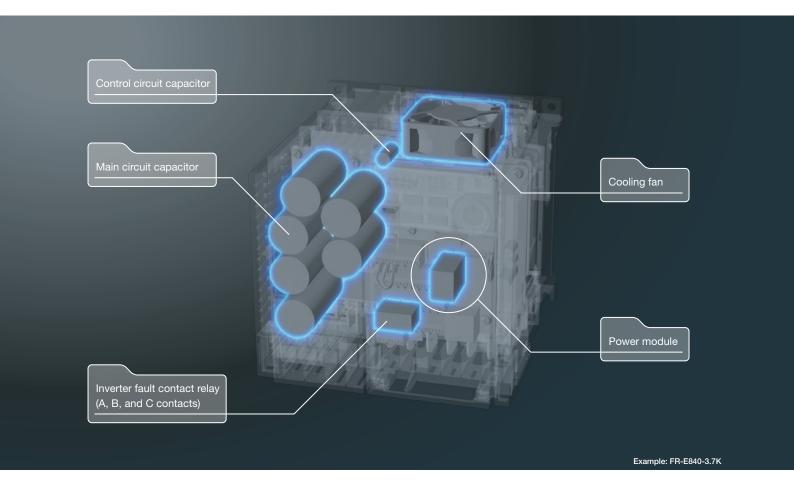






# Maintenance Improved maintainability

Functions for residual life diagnosis, predictive maintenance, and preventive maintenance support stable system operation.



#### Supporting scheduled maintenance planning

#### Control circuit board corrosion diagnosis

The world's first\*1 corrosive gas environment detection circuit\*2 makes it possible to identify signs of inverter damage caused by hydrogen sulfide or other corrosive gas. Equipment downtime will be reduced as the function notifies operators when the production environment needs to be improved (for coated models (-60) only).

- \*1: According to our investigation as of September 10, 2019.
- \*2: Patent pending.

#### Enhanced life diagnosis function

Availability of life diagnosis checks is extended. This enhanced diagnosis function ensures reliable operation of the system.

The design life of cooling fans and capacitors has been extended to 10 years\*3.

- \*3: Surrounding air temperature: annual average 40°C (free from corrosive gas, flammable gas, oil mist, dust and dirt)
  - Output current: 80% of the inverter rated current
  - Since the design life is a calculated value, it is not a guaranteed value.



E800-E

**E800-SCE** 



Sewage treatment plant

#### Extended 📕

- Main circuit capacitor online life diagnosis
- Inverter fault contact relay
   (A, B, and C contacts) life diagnosis
- Power module life diagnosis
- Control circuit capacitor life diagnosis
- Cooling fan life diagnosis
- Inrush current limit circuit life diagnosis

#### 2 Real-time monitoring for early fault detection

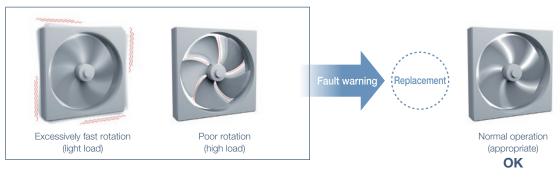
E800

E800-E E800-SCE

#### ► Load characteristics fault detection function

When a mechanical fault such as clogging of the filter occurs, the inverter outputs a warning or shuts off the output to prevent system damage.

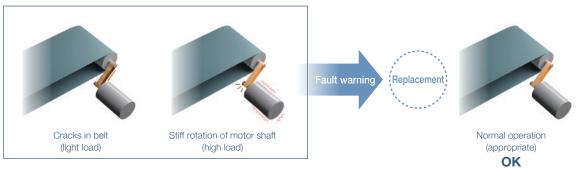
The speed-torque characteristic is stored while no fault occurs, enabling comparison between the measured data and the stored data.



#### Current detection function

Faults caused by stiff rotation of motor shaft (increased load) or cracks in the belt (decreased load) can be detected through the motor output current.

If the output current exceeds the predetermined value, a signal is output to inform the user of the faulty device.



#### 3 Supporting preventive maintenance of peripherals

E800

E800-E

E800-SCE

E800-SCE

#### Maintenance timer

The Maintenance timer signal is output when the inverter's cumulative energization time reaches the time period set with the parameter. This can be used as a guide for when the maintenance of the equipment should be conducted.

#### 4 Thorough customer support

#### ► FA Center network

Our global network offers reliable technical support and customer satisfaction. (Refer to page 42.)

#### Setup information web page

Our setup information web page provides easy access to manuals, videos, and outline dimension drawings (Refer to page 27.)



When a fault occurs, Al analysis and other diagnosis functions solve the problem quickly.



#### Streamlining the installation process

installation size

E800

E800-E E800-SCE

Power supply from USB port

2 Quick reaction to troubles

E800 E800-E E800-SCE

With the power supplied from the computer (USB bus power connection)\*1, parameters can be set while the main circuit power supply is OFF.

Maintenance can be performed quickly and safely.

\*1: The maximum SCCR should be 500 mA. A PU connector cannot be used during USB









#### 3 Easy and fast wiring

The installation size was determined to

assure exchangeability with the

interchange attachment options

replacement with the models of different size (FR-E820-3.7K, FR-E840-0.4K/0.75K/1.5K).

FR-E700 series. Installation

are available for facilitating

#### Spring clamp terminals

• Spring clamp terminals have been adopted for control circuit terminals for easy wiring. Furthermore, wires can be protected against loosening or contact faults due to vibrations during operation on a bogie or during transport. No additional screw tightening is required.

		FR-E800	FR-E800-E	FR-E800-SCE	
Input terminal		7	2	0	
Output terminal	Open collector	2	0	0	
terminal	Relay	1	1	1	



_	
2	Z

#### 4 Troubleshooting supported by AI technology

E800

E800-E

E800-SCE

#### ► Al fault diagnosis

The inverter is connected to the engineering software, FR Configurator2, in which Maisart\*1 (Mitsubishi Electric's AI technology) is integrated to analyze data and help identify the cause of a fault.



This function enables the fastest troubleshooting procedure without requiring any special skills, which contributes to downtime reduction.

\*1: Maisart is Mitsubishi Electric's brand of Al technology. The name stands for "Mitsubishi Electric's Al creates the State-of-the-ART in technology". This means that it is using our proprietary Al technology to make everything smarter.



#### Trouble analysis from a remote location

#### ▶ Trace function

The operating status (output frequency or other data) immediately before the protective function is activated can be stored in a data file.

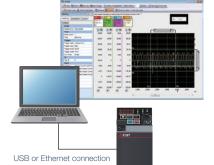
Users can read the data file in FR Configurator2 for graph display or send it by e-mail to someone away from the worksite, which facilitates the trouble analysis.

#### Clock function

Setting the time\*1 enables the user to specify the protective function activation time.

The date and time are also saved with the trace data, making the fault analysis easier.

\*1: The clock is reset at power-OFF.



E800-E

**E800-SCE** 

E800

25

# **Engineering tools**

### **Engineering software for** further ease of operation

The work efficiency can be improved for each of the design, operation, and maintenance processes.

#### FR Configurator2 for further ease of operation

Using FR Configurator2, easy-to-use software assisting anything from setup to maintenance, much more useful functions are available for users.

The function with the marking above is available in the free trial version (usable free of charge with limited functions). It can be downloaded at Mitsubishi Electric FA Global Website.

Function	Free trial version	Function
Parameter list	0	Convert
Diagnosis	0	Developer
Al fault diagnosis	×	USB memory
Graph	×	parameter copy
Batch monitor	×	Ethernet paramete
Test operation	0	iQSS backup file o
I/O terminal monitor	×	Help

A full functional trial version, which has the same functionality as the release version, is also offered for a limited period of 20 days

r setting

#### Life diagnosis check Free trial version Functions

Parts service life data is displayed in a dedicated window. A warning icon is shown in the alarm field of the parts recommended for replacement.

This can be used as a guideline to replace long life parts.



#### Graph function—Automatic sampling when a fault occurs

Waveform graph data immediately before the protective function is activated can be automatically

Graph display and log analysis are available using the stored trace data.



#### **Ethernet parameter setting**

Free trial version Functions

Inverters in the same subnet mask are automatically detected, supporting easy network setting.



2) Enter the network No., station No., IP address, and subnet mask.



#### Diagnostics (Fault history)

Fault records in the inverter can be displayed. When the clock function or CC-Link IE TSN communication is used, the time of fault occurrence can be displayed, too. It is possible to check the occurrence time and the type of faults, which is helpful in identifying causes of faults.



#### 2 Further facilitating operation with your smartphone

E800 E800-E E800-SCE

► Setup information web page

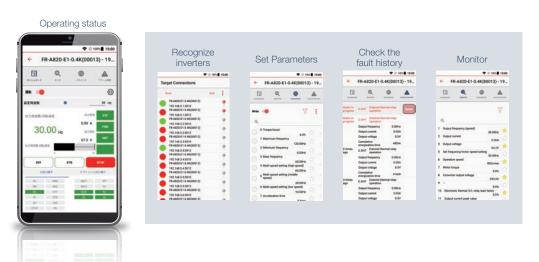
Users can scan the QR code on the product to directly access the setup information. Manuals, videos, and outline dimension drawings are available. (FR-E800 series inverters)



Wireless access with inverters from a remote location enables setting or changing of parameters, starting and stopping, and monitoring on the screen of mobile devices.

Users can easily monitor the inverter operation by checking data such as the running frequency and status of input and output terminals at a glance in one screen.

Wireless communication equipment must be prepared in the system that includes the inverter.



# **Engineering tools**

### **Engineering software for** further ease of operation

The work efficiency can be improved for each of the design, operation, and maintenance processes.

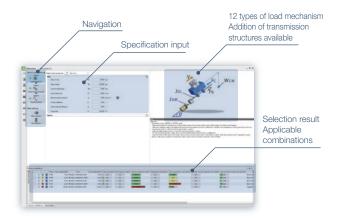
#### 3 Further facilitating operation with the capacity selection software To be supported soon

Users can select motors by entering data of mechanical configuration, specifications, and operating patterns. Applicable combinations include inverters, sersorless servo drive units, and AC servo amplifiers.

The most suitable combination can be selected from the selection result. The software also supports multi-axis

Twelve types of load mechanism such as a ball screw or a rack and pinion are selectable.

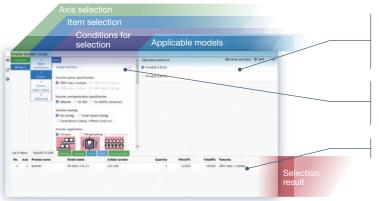
Selection is available by following the steps from 1 to 3. When users include the power regeneration common converter or other applicable converter, the capacity of the converter can be selected at the same time.



#### 4 Further facilitating operation with the selection guide software To be supported soon

E800-SCE E800-E

Advanced search for optimum inverters is available. Users can select inverters by entering data such as the motor capacity and current value and specifying specifications. The time spent on inverter selection can be reduced.



Applicable models will change in real time according to changes made to entries. Users do not have to fill all fields for selection. Applicable models will be selected according to the data entered

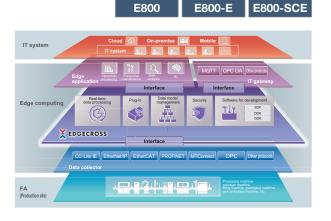
Users can select the items to enter to set conditions for selection by folding or unfolding windows. Both easy setting and detailed setting are available.

Users can select one of the applicable models to register it as the selection result.

#### 5 Further facilitating operation with **Edgecross**

Inverters and the system are integrated by maximizing the use of production data with edge computing, enabling solutions for various issues including productivity improvement and equipment maintenance.

- Integration and processing of data sent from various devices and systems in production lines
- Real-time feedback to production sites
- · Monitoring of field devices based on the know-how of production sites



#### 6 Further facilitating operation with GOT interaction functions To be supported soon

Enhanced compatibility between inverters and the GOT (human machine interface) brings various benefits to users.

Connection with the GOT2000 series can be established just by setting the station number. Other necessary settings are automatically done.

#### GOT **Drive**

E800-E E800-SCE

#### Less time spent on screen design work by importing sample screens

Various sample screens\*1 are available to enable parameter setting, batch monitor, measurement of load characteristics and so on using the GOT.

Using sample screens enables easy startup of the system.

\*1: Sample screens are included in the GT Works3 (Ver. 1.205P or later) package, or can be downloaded at Mitsubishi Electric FA Global Website.



#### Improving work efficiency without using a computer

Users can use the GOT to set up, adjust, and perform maintenance for inverters without using a computer.



#### Immediate warning of system errors

By storing the data of relationship between the output frequency and the torque during normal inverter operation, users can judge whether the load is operating in normal condition. By outputting out-of-range warnings if applicable, users can detect mechanical faults or perform maintenance.

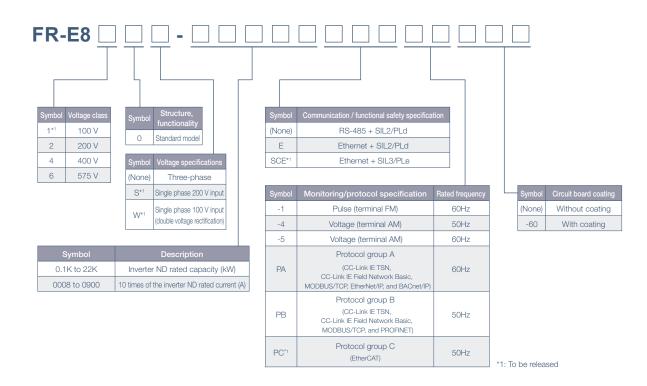
#### Reducing downtime by interacting with the GOT

Faults occurred in the inverter can be displayed on the GOT screen. When a fault occurs, it is possible to identify the cause immediately, which contributes to downtime reduction.





# Lineup



	lodel					Applic	able moto	r capacity	(ND ratin	g) (kW)				
M	0.1	0.2	0.4	0.75	1.5	2.2	3.7	5.5	7.5	11		18.5		
Three-phase 200 V	FR-E820-[]K(E)		•	•	•	•	•	•	•	•	0	0	0	0
Three-phase 200 V	FR-E820-[]KSCE	0	0	0	0	0	0	0	0	0	0	0	0	0
Thurst in large 400 V	FR-E840-[K(E) — — • •	•	•	•	•	•	0	0	0	0				
Three-phase 400 V	FR-E840-[]KSCE	_	_	0	0	0	0	0	0	0	0	0	0	0
Thurst where 575 \/	FR-E860-[]K(E)	_	_	_	•	•	•	•	•	•	_	_	_	_
Three-phase 575 V	FR-E860-[]KSCE	_	_	_	0	0	0	0	0	0	_	_	_	_
Single-phase 200 V	FR-E820S-[]K(E/SCE)	0	0	0	0	0	0	_	_	_	_	_	_	
Single-phase 100 V	FR-E810W-[]K(E/SCE)	0	0	0	0	_	_	_	_	_	_	_	_	_

 $\bullet$  : Released,  $\bigcirc$  : To be released,  $-\!\!\!-$  : Not applicable







# Rating

◆ Three-phase 200 V power supply

Ť			Table II	0.1K	0.2K	0.4K	0.75K	1.5K	2.2K	3.7K	5.5K	7.5K		
	MO	aei FK	-E820-[]	8000	0015	0030	0050	0800	0110	0175	0240	0330		
	able motor cap	acity	LD	0.2	0.4	0.75	1.1	2.2	3.0	5.5	7.5	11		
(kW)*1			ND	0.1	0.2	0.4	0.75	1.5	2.2	3.7	5.5	7.5		
	Rated capacit	y	LD	0.5	0.8	1.4	2.4	3.8	3.8 4.8 7.8		12.0	15.9		
	(kVA)*2		ND	0.3	0.6	1.2	2.0	3.2	4.4	7.0	9.6	13.1		
	Rated current	· (A)*7	LD	1.3 (1.1)	2 (1.7)	3.5 (3.0)	6.0(5.1)	9.6 (8.2)	12 (10.2)	19.6 (16.7)	30 (25.5)	40 (34)		
=	Rated Current	(A) 1	ND	0.8 (0.8)	1.5 (1.4)	3 (2.5)	5 (4.1)	8 (7)	11 (10)	17.5 (16.5)	24 (23)	33 (31)		
Output	Overload curr	ent	LD	120% 60 s, 1	120% 60 s, 150% 3 s (inverse-time characteristics) at surrounding air temperature of 50°C									
ŏ	rating*3		ND	150% 60 s, 2	200% 3 s (inver	se-time chara	cteristics) at su	ırrounding air t	emperature of	50°C				
	Rated voltage	*4		Three-phase	Three-phase 200 to 240 V									
	Regenerative	Brake tr	ansistor	-	Built-in									
	braking Maximur		ım brake torque*5	150%	150%		50% 20%							
	Rated input AC voltage/frequency			Three-phase 200 to 240 V 50 Hz / 60 Hz										
	Permissible AC voltage fluctuation			170 to 264 V 50 Hz / 60 Hz										
	Permissible fr	equency	fluctuation	±5%										
<u>&gt;</u>		LD	Without DC reactor	1.9	3.0	5.1	8.2	13	16	26	37	49		
supply	Rated input	LD	With DC reactor	1.3	2.0	3.5	6.0	9.6	12	20	30	40		
r Si	current (A)*8	ND	Without DC reactor	1.4	2.3	4.5	7.0	11	15	23	30	41		
Power		ND	With DC reactor	0.8	1.5	3.0	5.0	8.0	11	17.5	24	33		
8	Power	LD	Without DC reactor	0.7	1.1	1.9	3.1	4.8	6.2	9.7	14	19		
	supply	LD	With DC reactor	0.5	0.8	1.3	2.3	3.7	4.6	7.5	11	15		
	capacity	ND	Without DC reactor	0.5	0.9	1.7	2.7	4.1	5.7	8.8	12	16		
	(kVA)*6	ND	With DC reactor	0.3	0.6	1.1	1.9	3.0	4.2	6.7	9.1	13		
Protec	tive structure (	IEC 605	29)	Enclosed typ	e (IP20)	•	•	•	•	•	•			
Cooling	g system			Natural				Forced air						
Approx	imate mass (l	(g)		0.5	0.5	0.7	1.0	1.4	1.4	1.8	3.3	3.3		

#### Three-phase 400 V class

	Ma	dal ED	E940 II	0.4K	0.75K	1.5K	2.2K	3.7K	5.5K	7.5K			
	IVIO	ueirk	R-E840-[]	0016	0026	0040	0060	0095	0120	0170			
	able motor cap	acity	LD	0.75	1.5	2.2	3.0	5.5	7.5	11			
(kW)*1	,			0.4	0.75	3.7	5.5	7.5					
	Rated capacity		LD	1.6	2.7	4.2	5.3	8.5	13.3	17.5			
	(kVA)*2		ND	1.2	2.0	3.0	4.6	7.2	9.1	13.0			
	Rated current (A)*7  Overload current L rating*3		LD	2.1 (1.8)	3.5 (3.0)	5.5 (4.7)	6.9 (5.9)	11.1 (9.4)	17.5 (14.9)	23 (19.6)			
Ħ			ND	1.6 (1.4)	2.6 (2.2)	8 (7)	11 (10)	17.5 (16.5)	24 (23)	33 (31)			
			LD	120% 60 s, 150% 3 s (inverse-time characteristics) at surrounding air temperature of 50°C									
õ			ND	150% 60 s, 200% 3 s (inverse-time characteristics) at surrounding air temperature of 50°C									
	Rated voltage*4			Three-phase	380 to 480 V								
	Regenerative Brake		transistor	Built-in									
	braking	Maxim	um brake torque*5	100%	6 20%								
	Rated input AC voltage/frequency			Three-phase	380 to 480 V	50 Hz / 60 Hz							
	Permissible AC voltage fluctuation			323 to 528 V	323 to 528 V 50 Hz / 60 Hz								
	Permissible from	equenc	y fluctuation	±5%									
<u>&gt;</u>		LD	Without DC reactor	3.3	6.0	8.9	11	16	25	32			
효	Rated input		With DC reactor	2.1	3.5	5.5	6.9	11	18	23			
Power supply	current (A)*8	ND	Without DC reactor	2.7	4.4	6.7	9.5	14	18	25			
Νe		IND	With DC reactor	1.6	2.6	4.0	6.0	9.5	12	17			
Ъ	Power	LD	Without DC reactor	2.5	4.5	6.8	8.2	12	19	25			
	supply	LD	With DC reactor	1.6	2.7	4.2	5.3	8.5	13	18			
	capacity	ND	Without DC reactor	2.1	3.4	5.1	7.2	11	14	19			
	(kVA)*6 With DC reactor		1.2	2.0	3.0	4.6	7.2	9.1	13				
rotect	otective structure (IEC 60529)			Enclosed typ	e (IP20)								
Cooling	poling system			Natural		Forced air	Forced air						
Approximate mass (kg)				1.2	1.2	1.4	1.8	1.8	2.4	2.4			

- The applicable motor capacity indicated is the maximum capacity applicable for use of the Mitsubishis Electric 4-pole standard efficiency motor.

  The rated output capacity indicated assumes that the output voltage is 230 V for three-phase 200 V class and 440 V for three-phase 400 V class.

  The % value of the overload current rating indicated is the ratio of the overload current to the inverter's rated output current. For repeated duty, allow time for the inverter and motor to return to or below the temperatures under 100% load.

  The maximum output voltage does not exceed the power supply voltage. The maximum output voltage can be changed within the setting range. However, the pulse voltage value of the inverter output side voltage remains unchanged at about/2 that of the power supply.

  The braking torque indicated is a short-duration average torque (which varies with motor loss) when the motor alone is decelerated from 60 Hz in the shortest time and is not a continuous regenerative torque. When the motor is decelerated from the frequency higher than the base frequency, the average deceleration torque will reduce. Since the inverter does not contain a brake resistor, use the optional brake resistor when regenerative energy is large. A brake unit (FR-BU2) may also be used. (Option brake resistor cannot be used for 0.1 K and 0.2 K.)
- brake resistor cannot be used for 0.1K and 0.2K.)
  The power supply capacity varies with the value of the power supply side inverter impedance (including those of the input reactor and cables).
  Setting 2 kHz or more in **Pr. 72 PWM frequency selection** to perform low acoustic noise operation in the surrounding air temperature exceeding 40°C, the rated output current is the value in parenthesis.

  The rated input current is the value when at the rated output current. The input power impedances (including those of the input reactor and cables) affect the value.

# Rating

#### ♦ Three-phase 575 V class

Model FR-E860-[]				0.75K	1.5K	2.2K	3.7K	5.5K	7.5K		
			0017	0027	0040	0061	0090	0120			
Applicable motor capacity LD			1.5	2.2	3.7	5.5	7.5	11			
kW)*	1		ND	0.75	1.5	2.2	3.7	5.5	7.5		
· ·	Rated capacit	у	LD	2.5	3.6	5.6	8.2	11.0	15.9		
	(kVA)*2		ND	1.7	2.7	4.0	6.1	9.0	12.0		
	Rated current	(A)*7	LD	2.5 (2.1)	3.6 (3.0)	5.6 (4.8)	8.2 (7.0)	11 (9.0)	16 (13.6)		
Ħ		, ,	ND	1.7	2.7	4	6.1	9	12		
Output	Overload curr	ent	LD			e-time characteri					
õ	rating*3		ND	150% 60 s, 200% 3 s (inverse-time characteristics) at surrounding air temperature of 50°C							
	Rated voltage*4		Three-phase 5	Three-phase 525 to 600 V							
	Regenerative Brake tr		ransistor	Built-in							
	braking	Maximu	ım brake torque*5	100%	50%	50% 20%					
	Rated input AC voltage/frequency		Three-phase 575 V 60 Hz								
	Permissible AC voltage fluctuation		490 to 632 V 60 Hz								
	Permissible frequency fluctuation		±5%								
<u>&gt;</u>		LD	Without DC reactor	4.3	5.9	8.9	12	16	22		
슠	Rated input	LD	With DC reactor	2.5	3.6	5.6	8.2	11	16		
S	current (A)*8	ND	Without DC reactor	3.0	4.6	6.6	10	13	17		
ower supply		IND	With DC reactor	1.7	2.7	4.0	6.1	9.0	12		
Ğ	Power	LD	Without DC reactor	4.3	5.9	8.9	12	16	22		
	supply	בט	With DC reactor	2.5	3.6	5.6	8.2	11	16		
	capacity	ND	Without DC reactor	3.0	4.6	6.6	9.5	13	17		
	(KVA) O		With DC reactor	1.7	2.7	4.0	6.1	9.0	12		
Protective structure (IEC 60529)			Enclosed type	pe (IP20)							
- 9 )			Natural	Forced air	•	•	•				
Appro	ximate mass (l	(g)		1.9	1.9	1.9	2.4	2.4	2.4		

- The applicable motor capacity indicated is the maximum capacity applicable for use of the Mitsubishi Electric 4-pole standard efficiency motor.

  The rated output capacity indicated assumes that the output voltage is 575 V.

  The % value of the overload current rating indicated is the ratio of the overload current to the inverter's rated output current. For repeated duty, allow time for the inverter and motor to return to or below the temperatures under 100% load.
- and motor to return to or below the temperatures under 100% load.

  The maximum output voltage does not exceed the power supply voltage. The maximum output voltage can be changed within the setting range. However, the pulse voltage value of the inverter output side voltage remains unchanged at about 1/2 that of the power supply.

  The braking torque indicated is a short-duration average torque (which varies with motor loss) when the motor alone is decelerated from 60 Hz in the shortest time and is not a continuous regenerative torque. When the motor is decelerated from the frequency higher than the base frequency, the average deceleration torque will reduce. Since the inverter does not contain a brake resistor, use the optional brake resistor when regenerative energy is large. A brake unit (FR-BU2) may also be used. (Option
- brake resistor cannot be used for 0.1K and 0.2K.)

  The power supply capacity varies with the value of the power supply side inverter impedance (including those of the input reactor and cables).

  Setting 2 kHz or more in **Pr. 72 PWM frequency selection** to perform low acoustic noise operation in the surrounding air temperature exceeding 40°C, the rated output
- current is the value in parenthesis.

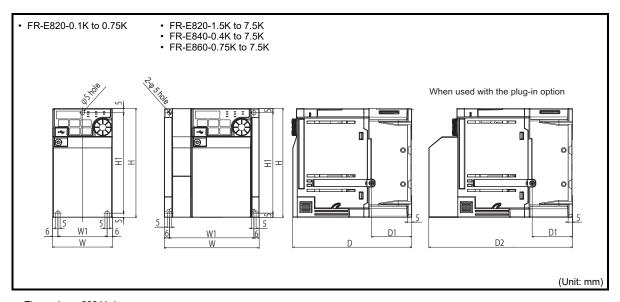
  The rated input current indicates a value at a rated output voltage. The impedance at the power supply side (including those of the input reactor and cables) affects the rated input current.

#### **MEMO**

# **Common specifications**

	Control method		Soft-PWM control/high carrier frequency PWM control
		Induction motor	V/F control, Advanced magnetic flux vector control, Real sensorless vector control
		PM motor	PM sensorless vector control
	Output frequency	Induction motor	0.2 to 590 Hz (The upper-limit frequency is 400 Hz under Advanced magnetic flux vector control, and Real sensorless vector control.)
	range	PM motor	0.2 to 400 Hz (not operable at maximum motor frequency or higher)
	Frequency setting	Analog input	0.015 Hz / 0 to 60 Hz (terminal 2, 4: 0 to 10 V / 12 bits) 0.03 Hz / 0 to 60 Hz (terminal 2, 4: 0 to 5 V / 11 bits, 0 to 20 mA / 11 bits)
Suc	resolution	Digital input	0.01 Hz
atic	Frequency	Analog input	Within ±0.2% of the max. output frequency (25°C ±10°C)
ij	accuracy	Digital input	Within 0.01% of the set output frequency
ol specifications	Voltage/frequen	cy characteristics	Base frequency can be set from 0 to 590 Hz. Constant-torque/variable torque pattern can be selected. (available with induction motors only)
Control	Starting torque	Induction motor	150% 0.5 Hz (Advanced magnetic flux vector control) 200% 0.3 Hz (0.4K to 3.7K), 150% 0.3 Hz (5.5K or more) (Real sensorless vector control)
		PM motor	50%
	Torque boost		Manual torque boost (available with induction motors only)
	Acceleration/de setting	celeration time	0 to 3600 s (acceleration and deceleration can be set individually), linear or S-pattern acceleration/deceleration mode
	DC injection	Induction motor	Operation frequency (0 to 120 Hz), operation time (0 to 10 s), operation voltage (0 to 30%) can be changed.
	brake	PM motor	Operation time (0 to 10 s) can be changed, operation voltage (operating current) is fixed.
	Stall prevention		Operation current level can be set (0 to 220% adjustable), whether to use the function or not can be selected.
	Torque limit leve		Torque limit value can be set (0 to 400% variable).
	Frequency	Analog input	Terminals 2 and 4: 0 to 10 V, 0 to 5 V, 4 to 20 mA (0 to 20 mA) are available.
	setting signal	Digital input	Input using the setting dial of the operation panel*1 Four-digit BCD or 16-bit binary (when used with option FR-A8AX E kit)
	Start signal		Forward and reverse rotation or start signal automatic self-holding input (3-wire input) can be selected.
	Input signal (Seven terminals/Two terminals)		Low-speed operation command, Middle-speed operation command, High-speed operation command, Output stop, Forward rotation command, Reverse rotation command, Inverter reset
ons	terrimais,		The input signal can be changed using Pr.178 to Pr.189 (input terminal function selection).
Operation specifications	Operational functions		Maximum and minimum frequency settings, multi-speed operation, acceleration/deceleration pattern, thermal protection, DC injection brake, starting frequency, JOG operation, output stop (MRS), stall prevention, regeneration avoidance, frequency jump, rotation display, automatic restart after instantaneous power failure, remote setting, automatic acceleration/deceleration, retry function, carrier frequency selection, fast-response current limit, forward/ reverse rotation prevention, operation mode selection, slip compensation, droop control, speed smoothing control, traverse, auto tuning, applied motor selection, RS-485 communication*1, Ethernet communication*2, PID control, easy dancer control, cooling fan operation selection, stop selection (deceleration stop/coasting), power-failure deceleration stop function, stop-on-contact control, PLC function, life diagnosis, maintenance timer, current average monitor, multiple rating, speed control, torque control, torque limit, safety stop function
	terminals)	or output (Two	Inverter running, Up to frequency The output signal can be changed using Pr.190 to Pr.196 (output terminal function selection). Fault codes of the inverter can be output (4 bits) from the open collector.
	Analog outp		-10 to +10 V / 12 bits
	Protective functions unction		Overcurrent trip during acceleration, Overcurrent trip during constant speed, Overcurrent trip during deceleration or stop, Regenerative overvoltage trip during acceleration, Regenerative overvoltage trip during acceleration, Regenerative overvoltage trip during deceleration or stop, Inverter overload trip, Motor overload trip, Heat sink overheat, Undervoltage, Input phase loss, Stall prevention stop, Loss of synchronism detection*3, Upper limit fault detection, Lower limit fault detection, Brake transistor alarm detection, Output side earth (ground) fault overcurrent, Output short circuit, Output phase loss, External thermal relay operation, Option fault, Communication option fault, Parameter storage device fault, PU disconnection, Retry count excess, CPU fault, OC detect level, inrush resistance overheat, Communication fault (inverter), USB communication fault, analog input error, Safety circuit fault, Overspeed occurrence*3, Speed deviation excess detection*3, Brake sequence fault*3, PID signal fault, Ethernet communication fault*2, Opposite rotation deceleration fault*3, Internal circuit fault
		Warning functions	Fan alarm, Stall prevention (overcurrent), Stall prevention (overvoltage), Regenerative brake pre-alarm*3, Electronic thermal relay function pre-alarm, PU stop, Maintenance timer warning, Parameter write error, Operation panel lock*3, Speed limit indication, Safety stop, Ethernet communication fault*2, Duplicate IP address*2, IP address fault*2
	Surrounding air	temperature	-20°C to +60°C (The rated current must be reduced at a temperature above 50°C.)
Environment	Ambient humidi	ty	95% RH or less (non-condensing) (With circuit board coating) 90% RH or less (non-condensing) (Without circuit board coating)
iror	Storage tempera	ature*4	-40°C to +70°C
En S	Atmosphere		Indoors (without corrosive gas, flammable gas, oil mist, dust and dirt, etc.)
	Altitude/vibration	n*5	Maximum 3000 m (Maximum 2000 m for the 575 V class), 5.9 m/s <sup>2</sup> or less at 10 to 55 Hz (directions of X, Y, Z axes)
_	Enabled only for standard models		

# **Outline Dimension Drawings**



• Three-phase 200 V class

Inverter model	W	W1	Н	H1	D	D1	D2
FR-E820-0.1K				118	80.5	42	108.1
FR-E820-0.2K	68	56					106.1
FR-E820-0.4K	00				112.5		140.1
FR-E820-0.75K			128		132.5		160.1
FR-E820-1.5K	108	96			135.5	46	163.1
FR-E820-2.2K	100				100.0		
FR-E820-3.7K	140	128			142.5	52.5	170.1
FR-E820-5.5K	180	164	260	244	165	71.5	192.6
FR-E820-7.5K							192.0

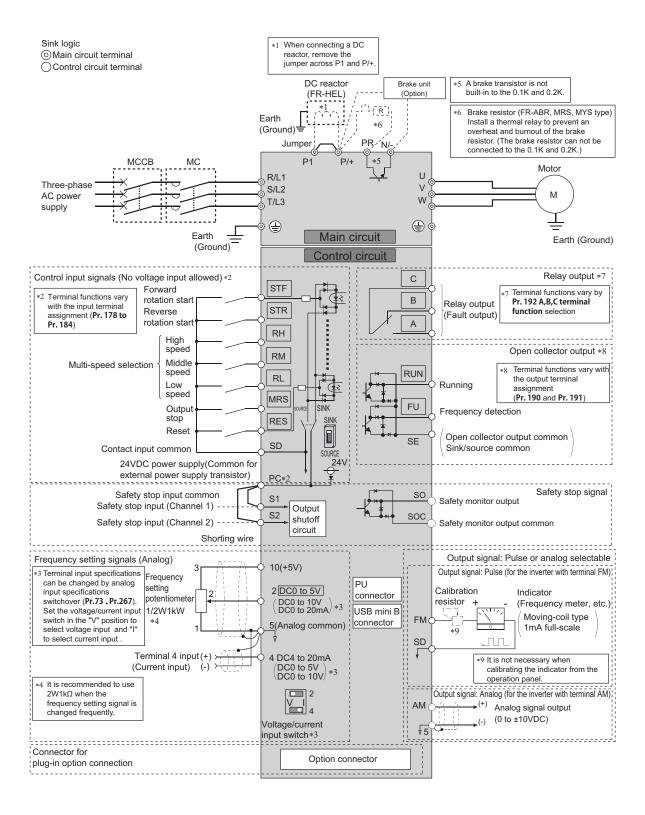
• Three-phase 400 V class

Inverter model	W	W1	Н	H1	D	D1	D2
FR-E840-0.4K		96	128	118	129.5	40	157.1
FR-E840-0.75K	108						
FR-E840-1.5K					135	46	163.1
FR-E840-2.2K	140	128	150	138		43.5	
FR-E840-3.7K	140						
FR-E840-5.5K	220 2	208	150	138	147	68	174.6
FR-E840-7.5K							

• Three-phase 575 V class

Three-phase 5/5 V class										
Inverter model	rter model W W1		Н	H1	D	D1	D2			
FR-E860-0.75K		128				43.5	163.1			
FR-E860-1.5K	140		150	138	135					
FR-E860-2.2K	1									
FR-E860-3.7K		208			147	68				
FR-E860-5.5K	220						174.6			
FR-E860-7.5K							l l			

# **Terminal Connection Diagram**



# Terminal Specifications

Ту	ре	Terminal Symbol	Terminal Name	Description					
		R/L1, S/L2, T/ L3	AC power input	Connect to the commercial power supply. Do not connect anything to these terr factor converter (FR-HC2) or the multifunction regeneration converter (FR-XC)	ninals when using the high power in common bus regeneration mode.				
*	_	U, V, W	Inverter output	Connect a three-phase squirrel-cage motor or PM motor.	Ţ.				
4	3	P/+, PR	Brake resistor connection	Connect a brake transistor (MRS type, MYS type, FR-ABR) across terminal cannot be connected to the 0.1K or 0.2K)	s P/+-PR. (The brake resistor				
2.	5 =	P/+, N/-	Brake unit connection	Connect the brake unit (FR-BU2), multifunction regeneration converter (FR-XC), or					
2	<u>8</u>	P/+, P1	DC reactor connection	Remove the jumper across terminals P/+-P1 and connect a DC reactor. What the jumper across terminals P/+ and P1 should not be removed.	nen a DC reactor is not connected,				
		<b>(</b>	Earth (Ground)	or earthing (grounding) the inverter chassis. Must be earthed (grounded).					
		STF*1	Forward rotation start	Turn on the STF signal to start forward rotation and turn it off to stop. When the STF and STR signals are turned on simultaneously, the stop					
		STR*1	Reverse rotation start	Turn on the STR signal to start reverse rotation and turn it off to stop.					
		RH, RM, RL*1	Multi-speed selection	Multi-speed can be selected according to the combination of RH, RM and RL signals.	Input resistance: 4.7 kΩ, voltage when contacts are open:				
		MRS*1	Output stop	Turn on the MRS signal (20ms or more) to stop the inverter output. Use to shut off the inverter output when stopping the motor by electromagnetic brake.	21 to 26 VDC, current when contacts are short-circuited: 4 to 6 mADC				
	input	RES*1	Reset	Use to reset alarm output provided when protective circuit is activated. Turn on the RES signal for more than 0.1s, then turn it off. It is possible to set the initial setting to "always enabled". By setting Pr. 75, reset can be set enabled only at fault occurrence. Recover about 1s after reset is cancelled.					
	Contact input		Contact input common (sink) (initial setting)	Common terminal for contact input terminal (sink logic) and terminal FM.					
	S	SD		Connect this terminal to the power supply common terminal of a transistor of device, such as a programmable controller, in the source logic to avoid male	output (open collector output) function by undesirable currents.				
			24VDC power supply common	Common output terminal for 24VDC 0.1A power supply (PC terminal). Isola	ted from terminals 5 and SE.				
input signal			External transistor common (sink) (initial setting)	Connect this terminal to the power supply common terminal of a transistor output (open collector output) device, such as a programmable controller, in the sink logic to avoid malfunction by undesirable currents.					
inpu		PC	Safety stop input terminal common	Common terminal for safety stop input terminals.	Power supply voltage range: 22.5 to 27 VDC,				
			Contact input common (source)	Common terminal for contact input terminal (source logic).	-permissible load current: 100 mA				
			24VDC power supply	Can be used as 24 VDC 0.1 A power supply.					
		10	Frequency setting power supply	Used as power supply when connecting potentiometer for frequency setting (speed setting) from outside of the inverter.	5 VDC ± 0.5 V permissible load current 10 mA				
	setting	2	Frequency setting (voltage)	Inputting 0 to 5 VDC (or 0 to 10 VDC) provides the maximum output frequency at 5 V (or 10 V) and makes input and output proportional. Use <b>Pr.73</b> to switch between input 0 to 5 VDC (initial setting) and 0 to 10 VDC input. Set the voltage/current input switch to the "I" position to select current input (0 to 20 mA).	Voltage input: Input resistance 10 k $\Omega$ ± 1 k $\Omega$ Permissible maximum voltage 20 VDC Current input: Input resistance 245 $\Omega$ ± 5 $\Omega$ Maximum permissible current 30 mA.				
	Frequency setting	4	Frequency setting (current)	Inputting 4 to 20 mADC (or 0 to 5 VDC, 0 to 10 VDC) provides the maximum output frequency at 20 mA and makes input and output proportional. This input signal is valid only when the AU signal is ON (terminal 2 input is invalid). To use the terminal 4 (current input at initial setting), assign "4" to any parameter from Pr.178 to Pr.184 (Input terminal function selection) before turning ON the AU signal. Use Pr.267 to switch among input 4 to 20 mA (initial setting), 0 to 5 VDC, and 0 to 10 VDC. Set the voltage/current input switch in the "V" position to select voltage input (0 to 5 V / 0 to 10 V).					
		5	Frequency setting common	Common terminal for the frequency setting signals (terminals 2 or 4). Do no	t earth (ground).				
	Relay	A, B, C	Relay output (fault output)	1 changeover contact output indicates that the inverter fault occurs. Fault: discontinuity across B-C (continuity across A-C), Normal: continuity across B-C (discontinuity across A-C)	Contact capacity 240 VAC 2A (power factor = 0.4) 30 VDC 1A				
_	Open collector	RUN	Inverter running	The output is in LOW state when the inverter output frequency is equal to or higher than the starting frequency (initial value; 0.5 Hz). The output is in HIGH state during stop or DC injection brake operation. *2	Permissible load 24 VDC (Maximum 27 VDC) 0.1 A				
signa	loo ue	FU	Frequency detection	The output is in LOW state when the inverter output frequency is equal to or higher than the preset detection frequency, and is in HIGH state when it is less than the preset detection frequency.*2	(a voltage drop is 3.4 V maximum when the signal is on)				
output signal	Ope	SE	Open collector output common	Common terminal of terminal RUN and FU.					
ō	Pulse	FM*3	For meter	Select one e.g. output frequency from	Permissible load current 1 mA 1440 pulses/s at 60 Hz				
	Analog	AM*3	Analog voltage output	monitor items. (Not output during inverter reset.) The output signal is proportional to the magnitude of the corresponding monitoring item.  Output item: output frequency (initial settling)	Output signal 0 to ±10 VDC, permissible load current 1 mA (load impedance 10 kΩ or more), resolution 8 bit				
		S1	Safety stop input (Channel 1)	Terminals S1 and S2 are used for the safety stop input signal for the safety relay module. Terminals S1 and S2 are used at the same time (dual	Input resistance 4.7 kΩ Voltage when contacts are open				
200	p signal	S2	Safety stop input (with 24 VDC input) (Channel 2)	channel). Inverter output is shutoff by shortening/opening between terminals S1 and SIC, or between S2 and SIC. In the initial status, terminals S1 and S1C are shorted with terminal PC by shorting wires. Terminal SIC is shorted with terminal SN. Remove the shorting wires and connect the safety relay module when using the safety stop function.	21 to 26 VDC Current when contacts are short-circuited 4 to 6 mADC				
14030	Salety stop signal	SO	(open collector output)	Indicates the safety stop input signal status. Switched to LOW when the status is other than the internal safety circuit failure. Refer to the FR-E800 Instruction Manual (Functional Safety) (BCN- A23488-000) when the signal is switched to HIGH while both terminals S1 and S2 are open. (Please contact your sales representative for the manual.)	Permissible load 24 VDC (maximum 27 VDC) 0.1 A (The voltage drop is 3.4 V at maximum while the signal is ON.)				
		soc	Safety monitor output terminal common	Common terminal for terminal SO.					
1	lication	_	PU connector	With the PU connector, RS-485 communication can be made. Conforming standard: EIA-485 (RS-485) - Transmission format: Multi-drop Communication speed: 300 to 115200bps · Overall extension: 500m	op link				
	Communication	_	USB connector*4	USB connection with a personal computer can be established. Setting, mor can be performed using FR Configurator2. Interface: conforms to USB 1.1 · Transmission Speed: 12 Mbps · Connector: USB mini B connector (receptacle mini B type)	itoring and testing of the inverter				
		minal functions o	on he calcuted value Dr 470	to Pr.184 (Input terminal function selection)					

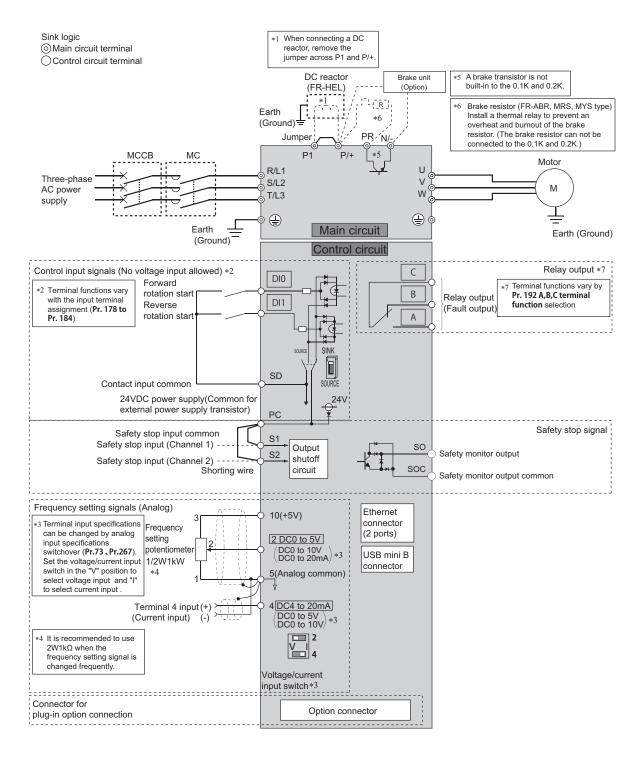
Terminal functions can be selected using Pr.178 to Pr.184 (Input terminal function selection).

An open collector transistor is ON (conductive) in LOW state. The transistor is OFF (not conductive) in HIGH state.

Terminal FM is provided for the FM type inverter. Terminal AM is provided for the AM type inverter.

USB bus power connection is available. The maximum SCCR should be 500 mA. A PU connector cannot be used during USB bus power connection.

# Terminal Connection Diagram



# Terminal Specifications EXOLE

Ту	ре	Terminal Symbol	Terminal Name		Description							
		R/L1, S/L2, T/L3	AC power input	Connect to the commercial power supp power factor converter (FR-HC2) or the regeneration mode.								
Main circuit		U, V, W	Inverter output	Connect a three-phase squirrel-cage m Connect a brake transistor (MRS type,		ole D/± DD /The brake resister						
	5	P/+, PR	Brake resistor connection	cannot be connected to the 0.1K or 0.2	K)	•						
M di di	5	P/+, N/-	Brake unit connection	Connect the brake unit (FR-BU2), multi (FR-HC2).	,	, , ,						
_		P/+, P1	DC reactor connection	emove the jumper across terminals P/+-P1 and connect a DC reactor. When a DC reactor is not connected, e jumper across terminals P/+ and P1 should not be removed.								
		<b>(</b>	Earth (Ground)	For earthing (grounding) the inverter ch	or earthing (grounding) the inverter chassis. Must be earthed (grounded).							
		DI0*1	Forward rotation start	Turn on the DI0 signal to start forward rotation and turn it off to stop.	Input resistance: 4.7 kΩ, voltage when contacts are open:							
		DI1*1	Reverse rotation start	Turn on the DI1 signal to start reverse	turned on simultaneously, the stop command is given.	21 to 26 VDC, current when contacts are short-circuited: 4 to 6 mADC						
			Contact input common (sink) (initial setting)	ommon terminal for contact input terminal (sink logic).								
	put	SD	External transistor common (source)	Connect this terminal to the power supp such as a programmable controller, in t								
	Contact input		24 VDC power supply common	Common output terminal for 24 VDC 0.	·							
	Cont		External transistor	Connect this terminal to the power supp								
			common (sink) (initial setting)	output (open collector output) device, s in the sink logic to avoid malfunction by		Dawar aynah yaltaga ranga						
		PC	Safety stop input terminal common	Common terminal for safety stop input	terminals.	Power supply voltage range: 22.5 to 27 VDC, permissible load current: 100 mA						
input signal			Contact input common (source)	Common terminal for the contact input	permissible load current. 100 mA							
but s			24 VDC power supply	Can be used as 24 VDC 0.1 A power s	5 VDC ± 0.5 V							
i		10	Frequency setting power supply	setting (speed setting) from outside of t	Jsed as power supply when connecting potentiometer for frequency setting (speed setting) from outside of the inverter.							
	etting	2	Frequency setting (voltage)	Inputting 0 to 5 VDC (or 0 to 10 V) prov frequency at 5 V (10 V) and makes inpu Use Pr. 73 to switch between input 0 to VDC input. Set the voltage/current inpu current input (0 to 20 mA).	Voltage input: Input resistance 10 k $\Omega$ ± 1 k $\Omega$ Permissible maximum voltage							
	Frequency setting	4	Frequency setting (current)	Inputting 0 to 20 mADC (or 0 to 5 V / 0 output frequency at 20 mA makes input signal is valid only when the AU signal i use terminal 4 (initial setting is current i Pr.179 (input terminal function selectior 267 to switch from among input 4 to 20 0 to 10 VDC. Set the voltage/current in select voltage input (0 to 5 V / 0 to 10 V	20 VDC Current input: Input resistance 245 $\Omega$ ± 5 $\Omega$ Maximum permissible current							
		5	Frequency setting common	Common terminal for the frequency set	not earth (ground).							
output signal	Relay	A, B, C	Relay output (fault output)	1 changeover contact output indicates   Fault: discontinuity across B-C (continu Normal: continuity across B-C (disconti	ity across A-C),	Contact capacity 240 VAC 2 A (power factor = 0.4) 30 VDC 1 A						
		S1	Safety stop input (Channel 1)	Terminals S1 and S2 are used for the sa relay module. Terminals S1 and S2 are	Input resistance 4.7 kΩ Voltage when contacts are open							
ledo	181181	S2	Safety stop input (with 24 VDC input) (Channel 2)	terminals S1 and SIC, or between S2 a terminals S1 and S2 are shorted with te Terminal SIC is shorted with terminal S	relay module. Terminals S1 and S2 are used at the same time (dual channel). Inverter output is shutoff by shortening/opening between terminals S1 and SIC, or between S2 and SIC. In the initial status, terminals S1 and S2 are shorted with terminal PC by shorting wires. Terminal SIC is shorted with terminal SD. Remove the shorting wires and connect the safety relay module when using the safety stop function.							
Safaty eton cional	calcit stop s	so	Safety monitor output (open collector output)	Switched to LOW when the status is of failure. Switched to HIGH during the int (LOW is when the open collector outpu HIGH is when the transistor is OFF (no E800 Instruction Manual (Functional Sa	Indicates the safety stop input signal status. Switched to LOW when the status is other than the internal safety circuit failure. Switched to HIGH during the internal safety circuit failure status. (LOW is when the open collector output transistor is ON (conducted). HIGH is when the transistor is OFF (not conducted).) Refer to the FR- E800 Instruction Manual (Functional Safety) (BCN-A23488-000) when the signal is switched to HIGH while both terminals S1 and S2 are open.							
		soc	Safety monitor output terminal common	Common terminal for terminal SO.	,							
nontecinimamo			Ethernet connector (2-port) *2	Category: 100BASE-TX/10BASE-T Data transmission speed: 100 Mbps ( Transmission method: Baseband Maximum segment length: 100m betw Number of cascade connection stage: Interface: RJ-45 Number of interfaces available: 1 IP version: IPv4	Communication can be made via Ethernet.  Category: 100BASE-TX/10BASE-T  Data transmission speed: 100 Mbps (100BASE-TX) / 10 Mbps (10BASE-T)  Transmission method: Baseband  Maximum segment length: 100m between the hub and the inverter  Number of cascade connection stages: Up to 2 (100BASE-TX) / up to 4 (10BASE-T)  Interface: RJ-45  Number of interfaces available: 1							
2	5	_	USB connector *3	can be performed using FR Configurate Interface: conforms to USB 1.1 · Tran	IP version: IPv4  ISB connection with a personal computer can be established. Setting, monitoring and testing of the inverter an be performed using FR Configurator2.  Interface: conforms to USB 1.1 · Transmission Speed: 12 Mbps  Connector: USB mini B connector (receptacle mini B type)							

Terminal functions can be selected using Pr.178, Pr.179 (Input terminal function selection). Do not connect the parameter unit. The inverter may be damaged. USB bus power connection is available. The maximum SCCR should be 500 mA.

# **Option List**

By fitting the following options to the inverter, the inverter is provided with more functions.

	Nama	Type	Applications	Арр	olicable	Inverter	Remarks			
	Name	Type	Applications	E800	E800-E	E800-SCE	Remarks			
	Vector control Orientation control Encoder feedback control	FR-A8AP E kit	Vector control can be performed for encoder-equipped motors (induction motors). The main spindle can be stopped at a specified position (orientation) in combination with an encoder. The motor speed is sent back and the speed is maintained constant.	0	0	0				
Type	16-bit digital input	FR-A8AX E kit	This input interface sets the high frequency accuracy of the inverter using an external BCD or binary digital signal.  BCD code 3 digits (maximum 999)  BCD code 4 digits (maximum 9999)  Binary 12 bits (maximum FFFH)  Binary 16 bits (maximum FFFFH)	•	•	0	Shared among all			
Plug-in Type	Digital output Extension analog output FR-A8AY E kit		This option provides the inverter with open collector outputs selected from among the standard output signals. This option adds 2 different signals that can be monitored such as the output frequency and output voltage. 20mADC or 10VDC meter can be connected.	•	•	0	models			
	Relay output	FR-A8AR E kit	Output any three output signals available with the inverter as standard from the relay contact terminals.	•	•	0				
	CC-Link communication	FR-A8NC E kit	Th:4:	•	•	0				
	DeviceNet communication	FR-A8ND E kit	This option allows the inverter to be operated or monitored or the parameter setting to be changed from a computer or	0	0	0				
	PROFIBUS-DP communication	FR-A8NP E kit	programmable controller.	0	0	0				
	Liquid crystal display operation panel	FR-LU08 (-01)	Graphical operation panel with liquid crystal display	0	-	-				
	Parameter unit	FR-PU07	Interactive parameter unit with LCD display	0	-	-				
	Parameter unit with battery pack	FR-PU07BB (-L)	This parameter unit enables parameter setting without connecting the inverter to power supply.	0	-	-				
	Enclosure surface operation panel	FR-PA07	This operation panel enables inverter operation and monitoring of frequency, etc. from the enclosure surface	•	-	-				
	Parameter unit connection cable	FR-CB20[]	Cable for connection of operation panel or parameter unit [] indicates a cable length. (1m, 3m, 5m)	•	-	-	Shared among all models			
	Encoder cable Mitsubishi Electric vector control dedicated motor (SFV5RU)	FR-V7CBL[]	Connection cable for the inverter and encoder for Mitsubishi Electric vector control dedicated motor (SF-V5RU).  [] indicates a cable length. (5m, 15m, 30m)	0	0	0				
	USB cable	MR-J3USBCBL3M Cable length: 3 m	Amplifier connector Mini B connector (5-pin)  Amplifier connector A connector	•	• 0					
	Intercompatibility attachment	FR-E7AT 01/02/03	For installation of a FR-E800 series inverter to the installation holes of FR-A024/A044 series inverter.	•	•	0	3.7K or lower. The option's model varies with the inverter's model.			
type	Intercompatibility attachment	FR-E8AT03	For installation of a FR-E700/E800 inverter to the installation holes of FR-A024/A044/E700 inverter.	•	•	0	3.7K			
Stand-alone type	DIN rail attachment	FR-UDA 01 to 03	Attachment for installation on DIN rail	0	0	0	3.7K or lower. The option's model varies with the inverter's model.			
Sta	Panel through attachment	FR-E8CN 01 to 06	Using this attachment dissipates the inverter's heat by having the inverter heatsink protrude from the back side of the enclosure.	0	0	0				
	Totally enclosed structure specification attachment (IP40)	FR-E8CV 01 to 04	Installing the attachment to the inverter changes the protective structure of the inverter to the totally enclosed structure (IP40 equivalent as specified by JEM1030).	0	0	0				
	AC reactor	FR-HAL	For harmonic current reduction and inverter input power	<b>A</b>	<b>A</b>	0	All capacities. The option's model			
	DC reactor	FR-HEL	factor improvement	<b>A</b>	<b>A</b>	0	varies with the			
	EMC Directive compliant noise filter	SF, FR-E5NF, FR-S5NFSA	EMC Directive (EN 61800-3 C3) compliant noise filter	<b>A</b>	<b>A</b>	0	inverter's model.			
	EMC compliant EMC filter installation attachment					0				
	Radio noise filter	FR-BIF(H)	For radio noise reduction (connect to the input side)	•	•	0				
	Line noise filter	FR-BSF01, FR-BLF	For line noise reduction	•	•	0	All capacities.			
	Filterpack	FR-BFP2	Combination of power factor improving DC reactor, common mode choke, and capacitative filter	0	0	0	0.4K or higher of the three-phase power input model. The option's model varies with the inverter's model.			
			Supported o: To be supported soon ★ : Support			·				

•: Supported ○: To be supported soon ▲: Supported (UL/cUL not yet met) -: Not supported

	N	_	A P C	Арр	olicable	Inverter	Domonlo	
	Name	Туре	Applications	E800	E800-E	E800-SCE	Remarks	
	Brake resistor	MRS type, MYS type	For increasing the regenerative braking capability (permissible duty 3%ED)	•	•	0		
	High-duty brake resistor	FR-ABR	For increasing the regenerative braking capability (permissible duty 10%/6%ED)	<b>A</b>	<b>A</b>	0	0.4K or higher. The option's model	
	Brake unit, Resistor unit, Discharging resistor	FR-BU2, FR-BR, GZG, GRZG type	For increasing the braking capability of the inverter (for high-inertia load or negative load) Brake unit, electrical-discharge resistor and resistor unit are used in combination	•	•	0	varies with the inverter's model.	
Stand-alone type	Multifunction regeneration converter Dedicated stand-alone reactor Dedicated box-type reactor	FR-XC FR-XCL/FR-XCG FR-XCB	One inverter can handle harmonic suppression and power regeneration. Functions that match the application can be selected by combining the inverter/converter with the dedicated reactor FR-XCB (box-type) or FR-XCL/FR-XCG.	•	•	-	According to capacities	
Stand	High power factor FR-HC2 converter		The high power factor converter switches the converter section on/off to reshape an input current waveform into a sine wave, greatly suppressing harmonics. (Used in combination with the standard accessory.)	• • -		capacilies		
	Surge voltage suppression FR-ASF FR-BMF		Filter for suppressing surge voltage on motor	•	•	0	400V: According to capacities 400V: 5.5K or higher According to capacities	
	Pilot generator		For tracking operation. 70 V / 35 VAC 500 Hz (at 2500 r/min)	•	•	0		
	Deviation sensor		For continuous speed control operation (mechanical deviation detection) Output 90VAC /90°		•	0		
Others	Analog frequency meter (64mm × 60mm)		Dedicated frequency meter (graduated to 130 Hz). Moving-coil type DC ammeter	•	-	ı	Shared among all	
Ç	Calibration resistor	Calibration resistor RV24YN 10kΩ For frequency meter calibration. Carbon film type B characteristic		•	•	0	models	
	FR Configurator2 (Inverter setup software)	Supports an inverter startup to maintenance.	•	•	0			
	FR Configurator Mobile (Mobile App for Inverters)				0	0		

•: Supported ○: To be supported soon ▲: Supported (UL/cUL not yet met) -: Not supported

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MEAMC Mitsubishi Electric Automation Manufacturing (Changshu) Co., Ltd.

MEATH Mitsubishi Electric Automation (Thailand) Co., Ltd.



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